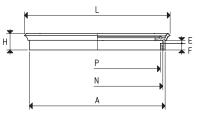
These cups represent a true mobile clamping system. They are composed of:

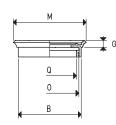
- A sturdy anodised aluminium support with a wide surface at the base limited by a seal whose purpose is to fix it to the bearing surface.
- A standard rectangular flat cup which is cold fitted onto the upper part of the support for gripping the load.

- Two quick couplings for vacuum connection. The detection of vacuum, for gripping and releasing the support, can be made via three-way vacuum valves or solenoid valves.

All cups with self-locking support of this and other ranges with the gripping plane at the same height can be used simultaneously, even if they are of different types or have different sizes.



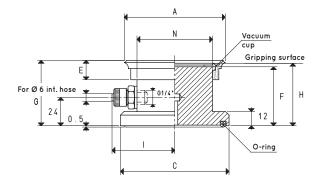


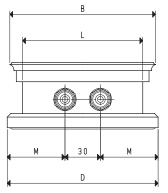


## SPARE VACUUM CUPS

Item	Force Kg	Volume cm <sup>3</sup>	Α	В	E	F	G	Н	L	М	N	0	Ρ	Q	<b>Weight</b> g
01 40 75 *	6.7	9.2	64	29	3	7.5	6.5	16.0	75	40	59	24	54	19	15.6
01 120 90 *	24.0	42.9	107	78	3	7.5	7.5	17.5	117	87	102	73	97	68	38.8
01 150 75 *	25.0	43.5	137	62	3	7.5	7.5	16.5	147	72	132	57	127	52	41.2

\* Complete the code indicating the compound: A= oil-resistant rubber; N= natural para rubber; S= silicone





## VACUUM CUPS WITH SELF-LOCKING SUPPORT

Item	<b>Force</b> Kg	A	В	C	D	E	F	G	H	I	L	М	N	Vacuum cup item	<b>O-ring</b> item	Weight Kg
16 40 75 *	6.7	41	76	48	83	16.0	51	56.5	54.5	30.5	55	26.5	20	01 40 75	00 16 09	0.260
16 120 90 *	24.0	90	120	98	128	17.5	50	57.0	54.5	56.0	102	49.0	70	01 120 90	00 16 10	1.166
16 150 75 *	25.0	75	150	83	144	16.5	50	57.0	54.5	48.0	130	57.0	55	01 150 75	00 16 10	1.177

\* Complete the code indicating the compound: A= oil-resistant rubber; N= natural para rubber; S= silicone

Note: The force of the vacuum cups indicated in the table represents 1/3 of the value of the theoretical force calculated at a level of vacuum of -75 KPa and a factor of safety 3. Transformation ratio: N (newton) = Kg x 9.81 (force of gravity) inch =  $\frac{mm}{25.4}$ ; pounds =  $\frac{g}{453.6} = \frac{Kg}{0.4536}$